

SAPOR-based MOR schemes with quadratic frequency dependence of excitation for FEM macromodels

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Presentation

- ➊ Introduction
- ➋ Model Order Reduction
- ➌ Numerical experiments
- ➍ Error Estimator
- ➎ Conclusions

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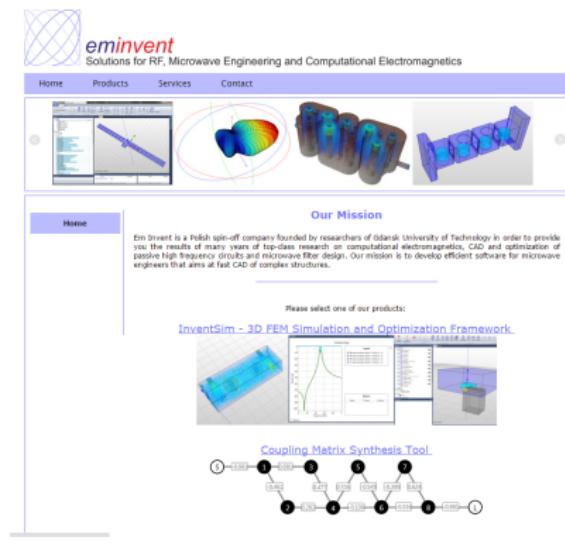
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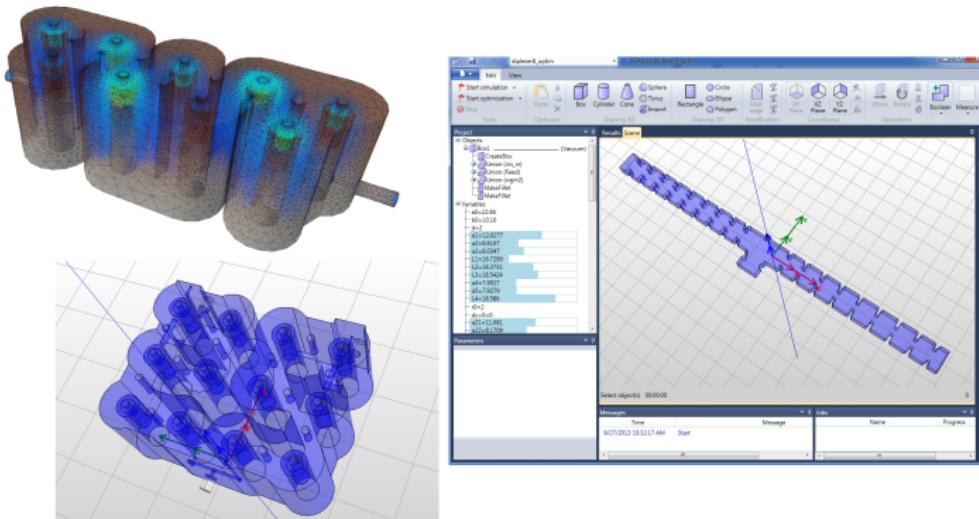
Introduction (1)

- FEM CAD EMinvent (<http://www.eminvent.com/>)



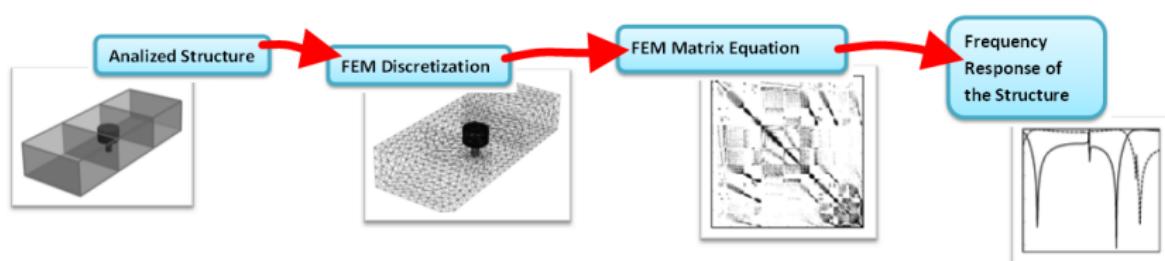
Introduction (2)

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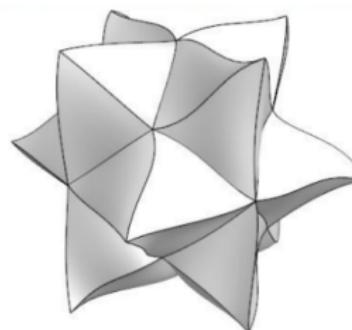
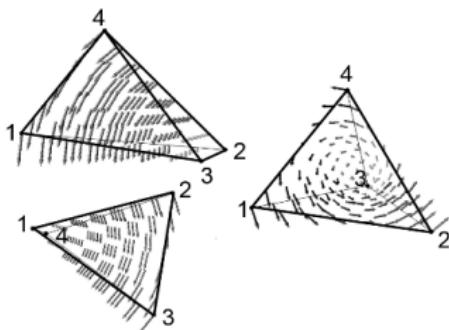
Introduction (3) - FEM

- The scheme of the FEM procedure



Introduction (4) FEM basis functions

- 2nd./ 3rd. order basis functions
- Curvilinear elements



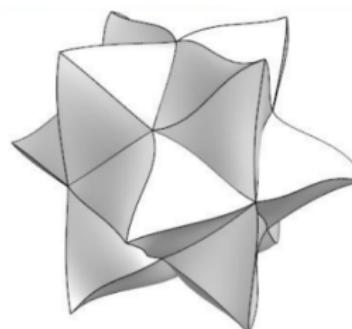
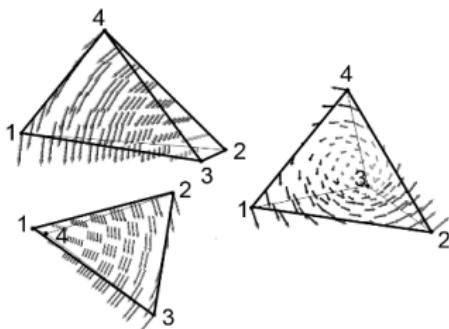
Space	Basis functions	Assoc.
\mathcal{V}_1	ϕ_i	{i}
\mathcal{V}_2	$\phi_i \phi_j$	{ij}
\mathcal{V}_3	$\phi_i \phi_j (\phi_i - \phi_j),$ $\phi_i \phi_j \phi_k$	{ij} {ijk}

Space	Basis functions	Assoc.
$\tilde{\mathcal{A}}_1$	$\phi_i \nabla \phi_j - \phi_j \nabla \phi_i$	{ij}
$\tilde{\mathcal{A}}_2$	$3\phi_j \phi_k \nabla \phi_i - \nabla(\phi_i \phi_j \phi_k),$ $3\phi_L \phi_i \nabla \phi_j - \nabla(\phi_i \phi_j \phi_k)$	{ijk}
$\tilde{\mathcal{A}}_3$	$4\phi_j \phi_k (\phi_j - \phi_k) \nabla \phi_i - \nabla(\phi_i \phi_j \phi_k (\phi_j - \phi_k)),$ $4\phi_i \phi_j (\phi_i - \phi_j) \nabla \phi_k - \nabla(\phi_j \phi_k \phi_i (\phi_k - \phi_i)),$ $4\phi_i \phi_j (\phi_i - \phi_j) \nabla \phi_k - \nabla(\phi_k \phi_i \phi_j (\phi_i - \phi_j)),$ $4\phi_i \phi_j \phi_k \nabla \phi_i - \nabla(\phi_i \phi_j \phi_k \phi_i),$ $4\phi_i \phi_j \phi_k \nabla \phi_j - \nabla(\phi_i \phi_j \phi_k \phi_j),$ $4\phi_i \phi_j \phi_k \nabla \phi_k - \nabla(\phi_i \phi_j \phi_k \phi_k)$	{ijkl}

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Introduction (5) FEM

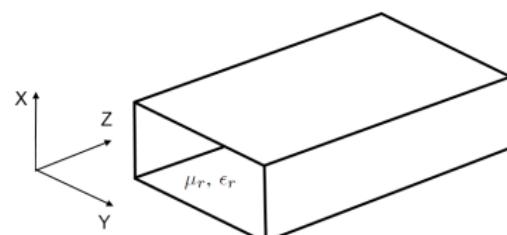
- Vectorial wave equation:

$$\nabla \times \frac{1}{\mu_r} \nabla \times \vec{E} - k_0^2 \epsilon_r \vec{E} = 0.$$

- The equivalent FEM matrix equation is obtained by discretizing the computational domain using a tetrahedral mesh and applying Galerkin method:

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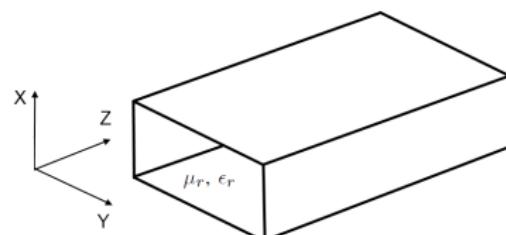
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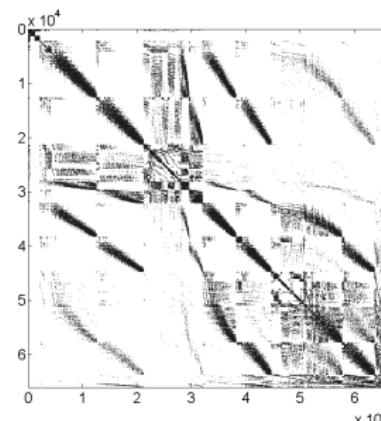


Introduction (5) FEM

- FEM matrix equation:

$$(\mathbf{K} - k^2 \mathbf{M}) \cdot \mathbf{x}(k) = \mathbf{b}(k)$$

- \mathbf{K} and \mathbf{M} (stiffness and mass matrices respectively) are $N \times N$ real, symmetric and sparse,
- \mathbf{b} is the excitation vector,
- \mathbf{x} is the vector of the unknown coefficients of the finite element basis functions.
- $k = 2\pi/\lambda$ is the wavenumber.

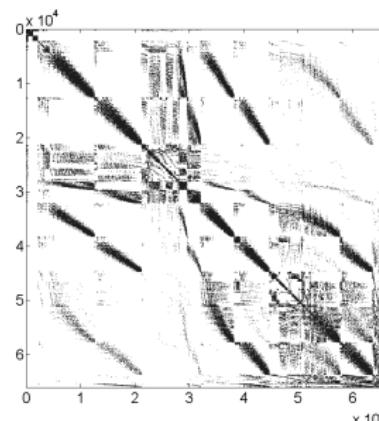


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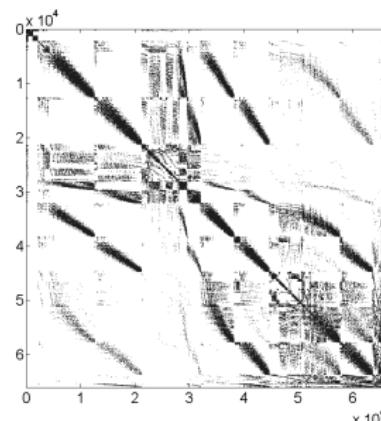


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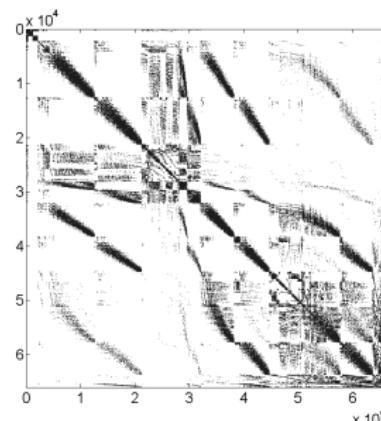
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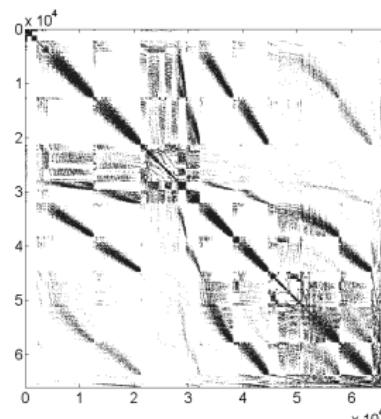


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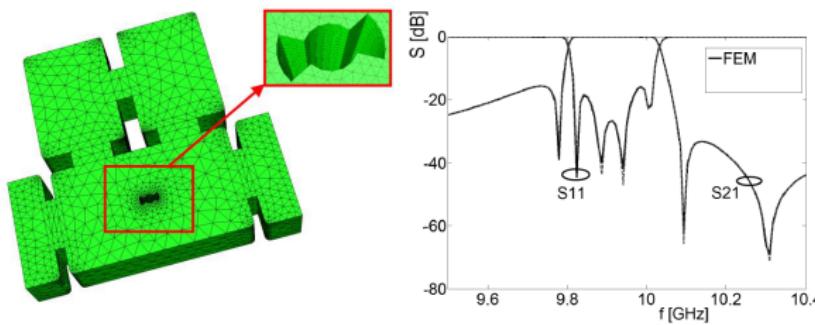
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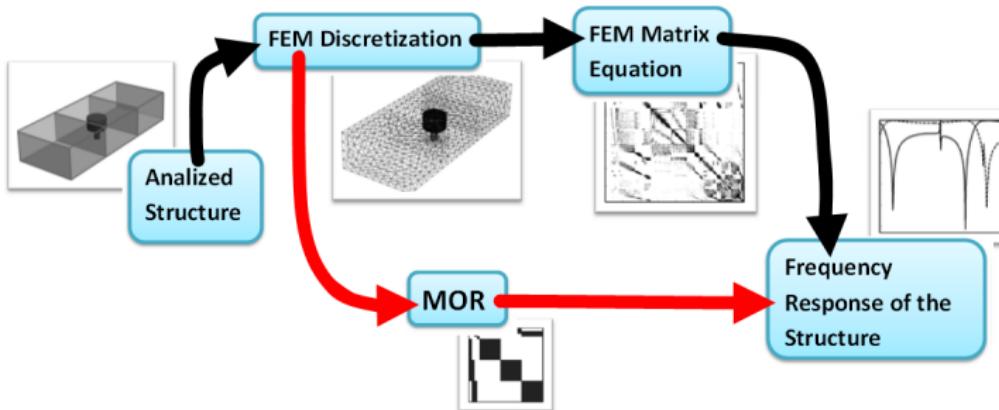
Introduction (6) - Numerical Example

- Number of variables: ca. 440.000
 - Number of frequency points: 101
 - Solution time: ca. 2h
 - i7, 16GB RAM



Goals (1)

- The scheme of the FEM-MOR procedure.



- Y. Zhu and A. C. Cangellaris, "Macro-elements for efficient FEM simulation of small geometric features in waveguide components," IEEE Trans. Microw. Theory Tech., vol. 48, no. 12, pp. 2254-2260, Dec. 2000.
 - V. de la Rubia and J. Zapata, "Microwave circuit design by means of direct decomposition in the finite-element method," IEEE Trans. Microw. Theory Tech., vol. 55, no. 7, pp. 1520-1530, Jul. 2007.
 - Lee, Shih-hao, "Efficient Finite Element Electromagnetic Analysis for High-Frequency/High-Speed Circuits And Multiconductor Transmission Lines". PhD Thesis. Director of Research: Jin, Jianming

Goals (2) - Features of the MOR

Features of the MOR:

- reliable
- automatic
- frequency independent
- suitable to optimization schemes

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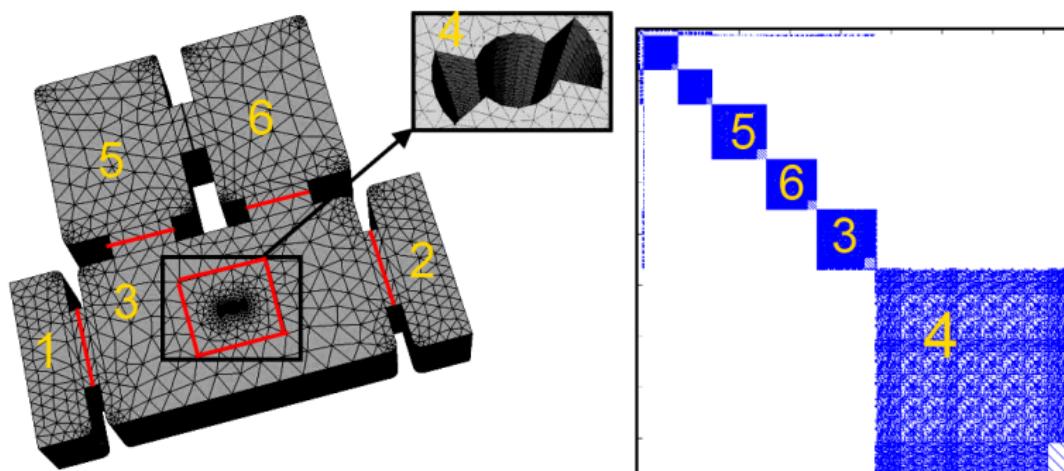
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MOR

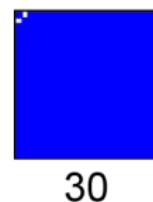
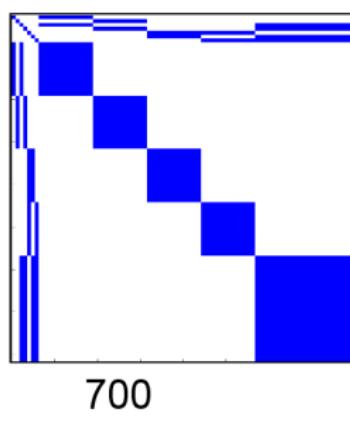
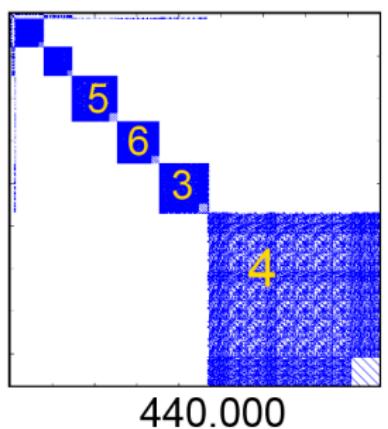
- Dividing the computational domain



440.000

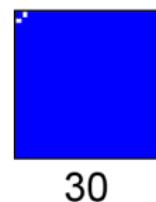
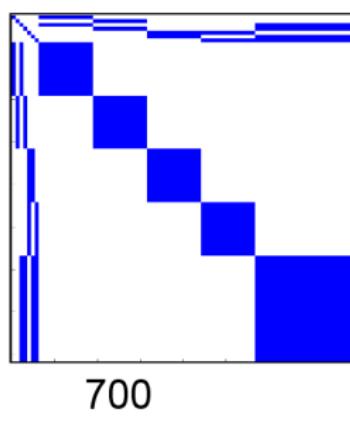
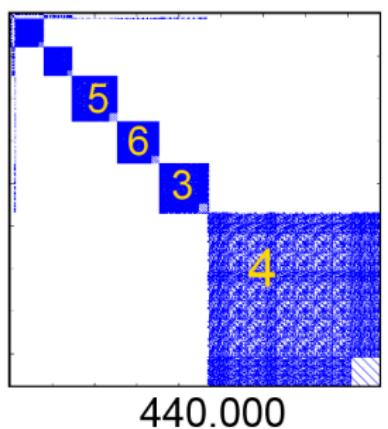
MOR (1) - number of variables

- Original FEM matrix
- After 1st reduction
- After 2nd reduction - matrix is 15.000 times smaller!



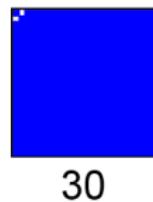
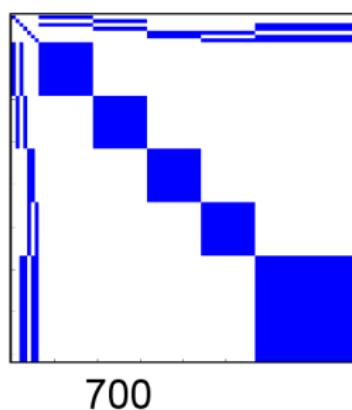
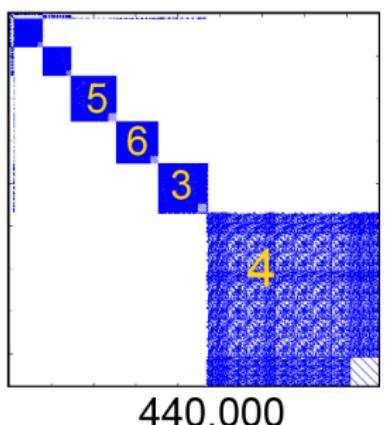
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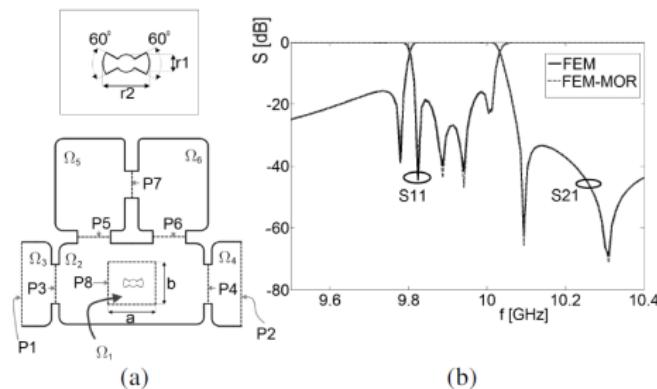
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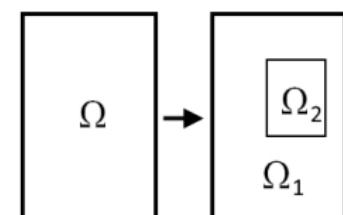
- Almost the same S-characteristics obtained by means of original FEM and FEM-MOR.



MOR (3)

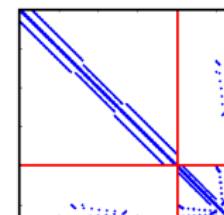
$$(\mathbf{K} - k^2 \mathbf{M}) \cdot \mathbf{x}(k) = \mathbf{b}(k)$$

- Subregion Ω_1 is separated from the outer region Ω_2 .
- Due to the separation of the subdomains the FEM matrix equation splits into:



$$\left(\begin{bmatrix} \mathbf{K}_1 & \mathbf{S}_K^T \\ \mathbf{S}_K & \mathbf{K}_2 \end{bmatrix} - k^2 \begin{bmatrix} \mathbf{M}_1 & \mathbf{S}_M^T \\ \mathbf{S}_M & \mathbf{M}_2 \end{bmatrix} \right) \cdot \begin{bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \end{bmatrix} = \begin{bmatrix} \mathbf{b} \\ \mathbf{0} \end{bmatrix},$$

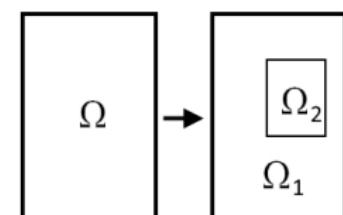
- The mesh edges that couple two separated subregions form four coupling matrices: \mathbf{S}_K , \mathbf{S}_M , \mathbf{S}_K^T and \mathbf{S}_M^T .
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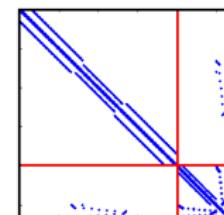
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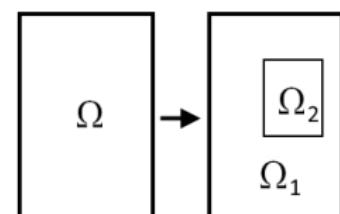


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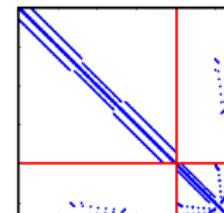
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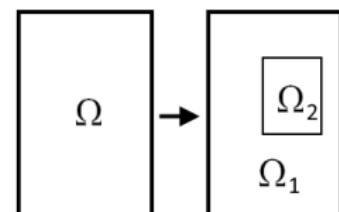


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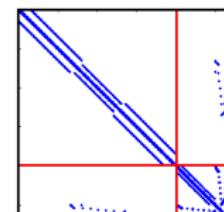
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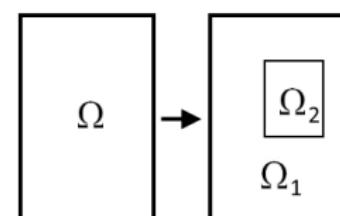


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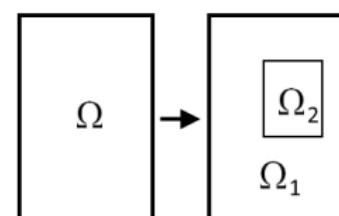
MOR (4)

- The number of variables in the separated region Ω_2 is N_2
- The number of variables in the outer region Ω_1 is N_1
- N_2 can be reduced by means of the REDUCTION algorithm
- input:
 - Matrices: K_2 , M_2 , S_K and S_M
 - q - the reduction order
 - s_0 - arbitrarily selected frequency.
- output: frequency independent orthonormal basis V



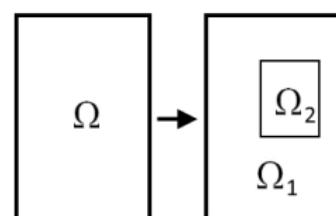
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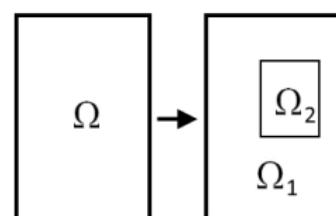
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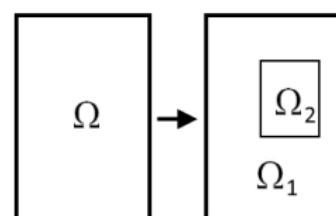
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- input:
 - Matrices: K_2 , M_2 , S_K and S_M
 - q - the reduction order
 - s_0 - arbitrarily selected frequency.
- output: frequency independent orthonormal basis V



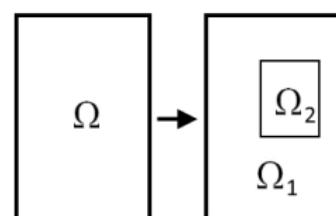
MOR (4)

- The number of variables in the separated region Ω_2 is N_2
- The number of variables in the outer region Ω_1 is N_1
- N_2 can be reduced by means of the REDUCTION algorithm
- input:
 - Matrices: K_2 , M_2 , S_K and S_M
 - q - the reduction order
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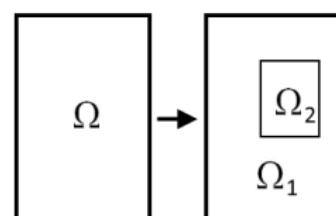
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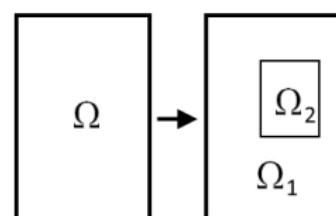
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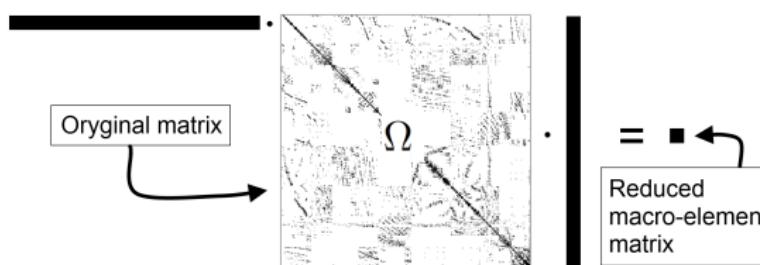
MOR (5)

- Matrices \mathbf{K}_2 , \mathbf{M}_2 , \mathbf{S}_K and \mathbf{S}_M from the FEM equation:

$$\left(\begin{bmatrix} \mathbf{K}_1 & \mathbf{S}_K^T \\ \mathbf{S}_K & \mathbf{K}_2 \end{bmatrix} - k^2 \begin{bmatrix} \mathbf{M}_1 & \mathbf{S}_M^T \\ \mathbf{S}_M & \mathbf{M}_2 \end{bmatrix} \right) \cdot \begin{bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \end{bmatrix} = \begin{bmatrix} \mathbf{b} \\ \mathbf{0} \end{bmatrix},$$

- can be reduced using the orthogonal basis \mathbf{V} :

$$\left(\begin{bmatrix} \mathbf{K}_1 & \mathbf{S}_K^T \cdot \mathbf{V} \\ \mathbf{V}^T \cdot \mathbf{S}_K & \mathbf{V}^T \cdot \mathbf{K}_2 \cdot \mathbf{V} \end{bmatrix} - k^2 \begin{bmatrix} \mathbf{M}_1 & \mathbf{S}_M^T \cdot \mathbf{V} \\ \mathbf{V}^T \cdot \mathbf{S}_M & \mathbf{V}^T \cdot \mathbf{M}_2 \cdot \mathbf{V} \end{bmatrix} \right) \cdot \begin{bmatrix} \mathbf{x}_1 \\ \tilde{\mathbf{x}}_2 \end{bmatrix} = \begin{bmatrix} \mathbf{b} \\ \mathbf{0} \end{bmatrix},$$



MOR (5)

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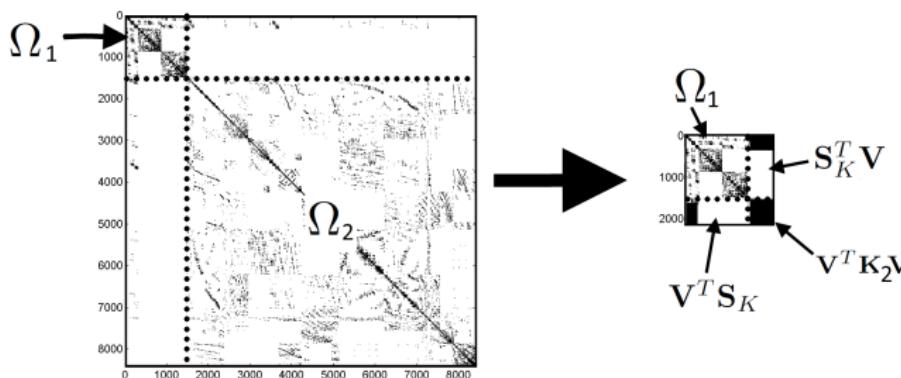
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MOR (6)

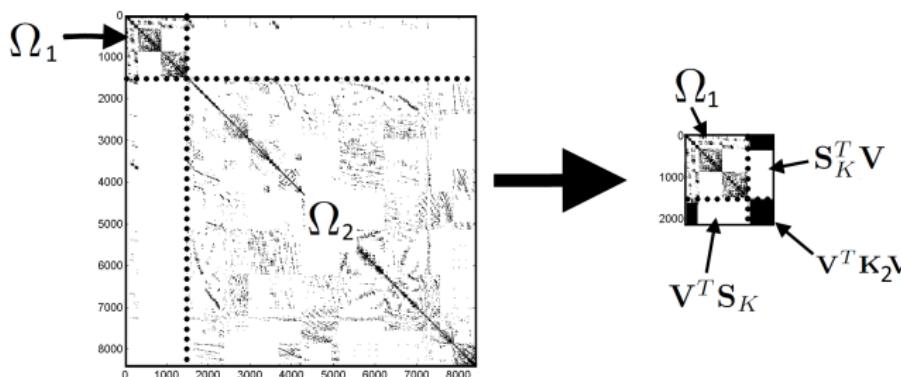
- System matrix after MOR:



- The reduced region is called a macro-element.
- The number of variables in macro-element is N_M .
- $N_M \ll N_2$

MOR (6)

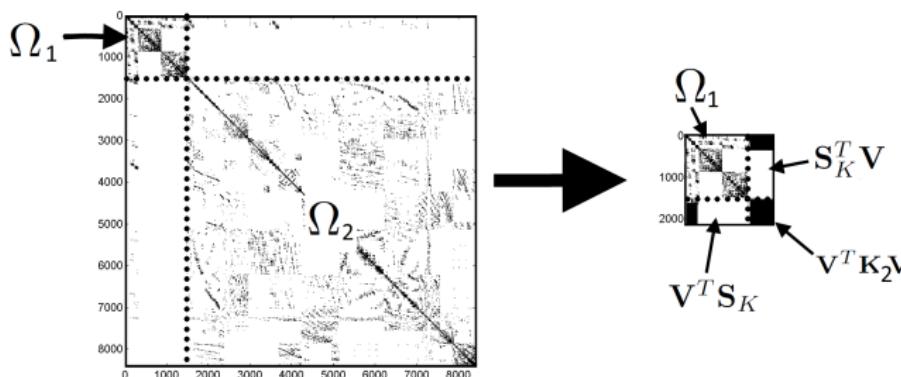
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MOR (7)

- The equation:

$$\left(\begin{bmatrix} \mathbf{K}_1 & \mathbf{S}_K^T \\ \mathbf{S}_K & \mathbf{K}_2 \end{bmatrix} - k^2 \begin{bmatrix} \mathbf{M}_1 & \mathbf{S}_M^T \\ \mathbf{S}_M & \mathbf{M}_2 \end{bmatrix} \right) \cdot \begin{bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \end{bmatrix} = \begin{bmatrix} \mathbf{b} \\ \mathbf{0} \end{bmatrix},$$

- can be represented as:

$$(\mathbf{K}_1 - k^2 \mathbf{M}_1) \cdot \mathbf{x}_1 + (\mathbf{S}_K^T - k^2 \mathbf{S}_M^T) \cdot \mathbf{x}_2 = \mathbf{b}$$

$$(\mathbf{K}_2 - k^2 \mathbf{M}_2) \cdot \mathbf{x}_2 = -(\mathbf{S}_K - k^2 \mathbf{S}_M) \cdot \mathbf{x}_1.$$

- Transmittance: $\mathbf{H}(k)$

$$\mathbf{x}_2 = \mathbf{H}(k) \mathbf{x}_1,$$

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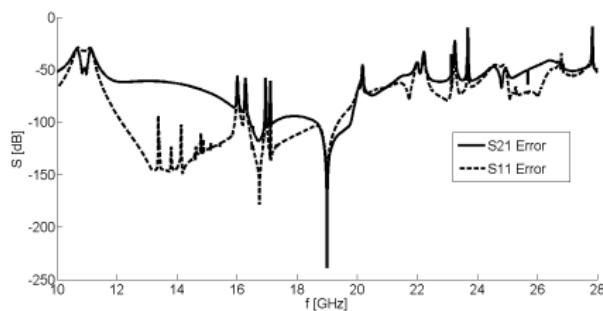
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MOR (8)

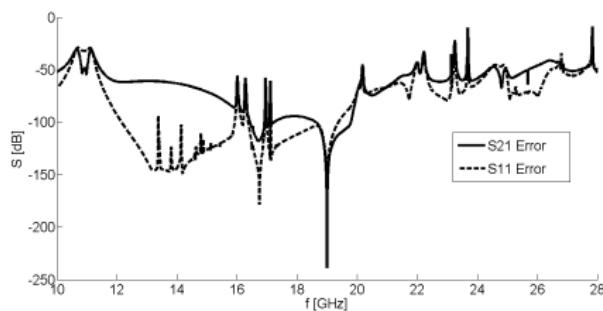
- Reduction algorithms: ENOR, SAPOR $\Rightarrow \checkmark$
- Error is low only for the center frequency!



- $(\mathbf{K} - k_0^2 M) \cdot \mathbf{x} = jk_0 \mathbf{b}$
- $(\mathbf{K}_2 - k^2 \mathbf{M}_2) \cdot \mathbf{x}_2 = -(\mathbf{S}_K - k^2 \mathbf{S}_M) \cdot \mathbf{x}_1 \Rightarrow$ Nonlinear RHS!

MOR (8)

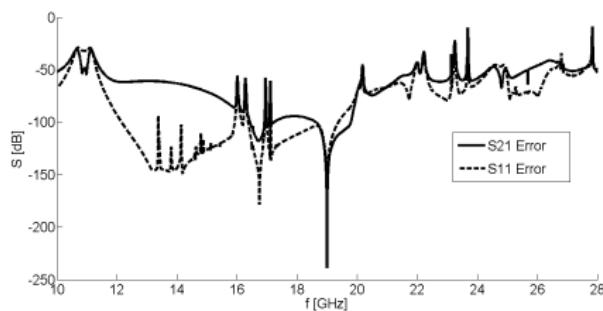
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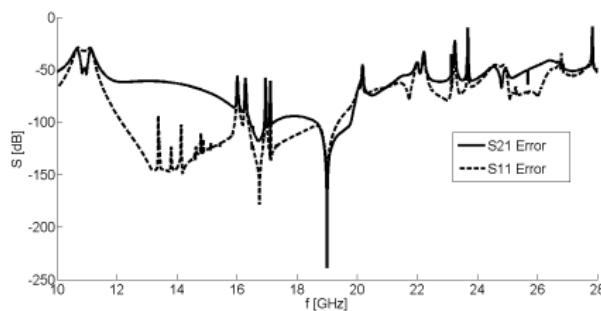
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MOR (9)

- Shifting the equation:

$$\mathbf{H}(k) = (\mathbf{K}_2 - k^2 \mathbf{M}_2)^{-1} \cdot (-\mathbf{S}_K + k^2 \mathbf{S}_M).$$

- with $k = k_0 + \sigma$, we obtain:

$$(\sigma^2 \mathbf{C} + \sigma \mathbf{D} + \mathbf{K}) \cdot \mathbf{H}(\sigma) = \sigma^2 \mathbf{B}_2 + \sigma \mathbf{B}_1 + \mathbf{B}_0,$$

- where:

$$\mathbf{C} = -\mathbf{M}_2; \quad \mathbf{D} = -2k_0 \mathbf{M}_2; \quad \mathbf{K} = \mathbf{K}_2 - k_0^2 \mathbf{M}_2;$$

$$\mathbf{B}_2 = \mathbf{S}_M; \quad \mathbf{B}_1 = 2k_0 \mathbf{S}_M; \quad \mathbf{B}_0 = -\mathbf{S}_K + k_0^2 \mathbf{S}_M;$$

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MOR (10)

- Introducing a new matrix: \mathbf{H}_z

$$\sigma \mathbf{C} \mathbf{H} + \mathbf{H}_z = \mathbf{B}_2 \sigma + \mathbf{B}_1$$

- we obtain:

$$(\mathbf{I} - \sigma \mathbf{A}) \begin{bmatrix} \mathbf{H} \\ \mathbf{H}_z \end{bmatrix} = \begin{bmatrix} \mathbf{K}^{-1} \mathbf{B}_0 \\ \mathbf{B}_1 \end{bmatrix} + \sigma \begin{bmatrix} 0 \\ \mathbf{B}_2 \end{bmatrix},$$

- where:

$$\mathbf{A} = \begin{bmatrix} \mathbf{K}^{-1} \mathbf{D} & \mathbf{K}^{-1} \\ \mathbf{C} & 0 \end{bmatrix}.$$

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MOR (11)

- By moving $(\mathbf{I} - \sigma \mathbf{A})$ to the RHS and performing a Maclaurin series expansion, we obtain:

$$\begin{bmatrix} \mathbf{H} \\ \mathbf{H}_z \end{bmatrix} = (\mathbf{I} + \sigma \mathbf{A} + \sigma^2 \mathbf{A}^2 + \sigma^3 \mathbf{A}^3 \dots) \cdot \left(\begin{bmatrix} \mathbf{K}^{-1} \mathbf{B}_0 \\ \mathbf{B}_1 \end{bmatrix} + \sigma \begin{bmatrix} 0 \\ \mathbf{B}_2 \end{bmatrix} \right).$$

- The block moments of \mathbf{H} : $\mathbf{H}_0, \mathbf{H}_1, \mathbf{H}_2 \dots$

$$\mathbf{H}_i = \left[\mathbf{A}^i \begin{bmatrix} 0 \\ \mathbf{B}_2 \end{bmatrix}, \quad \mathbf{A}^i \begin{bmatrix} \mathbf{K}^{-1} \mathbf{B}_0 \\ \mathbf{B}_1 \end{bmatrix} \right],$$

- The orthogonal basis \mathbf{V} of order q is spanned by $\mathbf{H}_0, \mathbf{H}_1, \mathbf{H}_2 \dots, \mathbf{H}_q$.

$$\mathbf{V}_q = [\mathbf{H}_1, \mathbf{H}_2, \mathbf{H}_3, \dots, \mathbf{H}_q].$$

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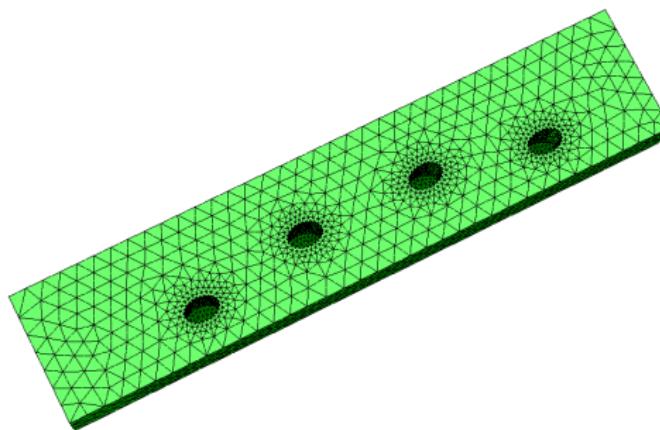
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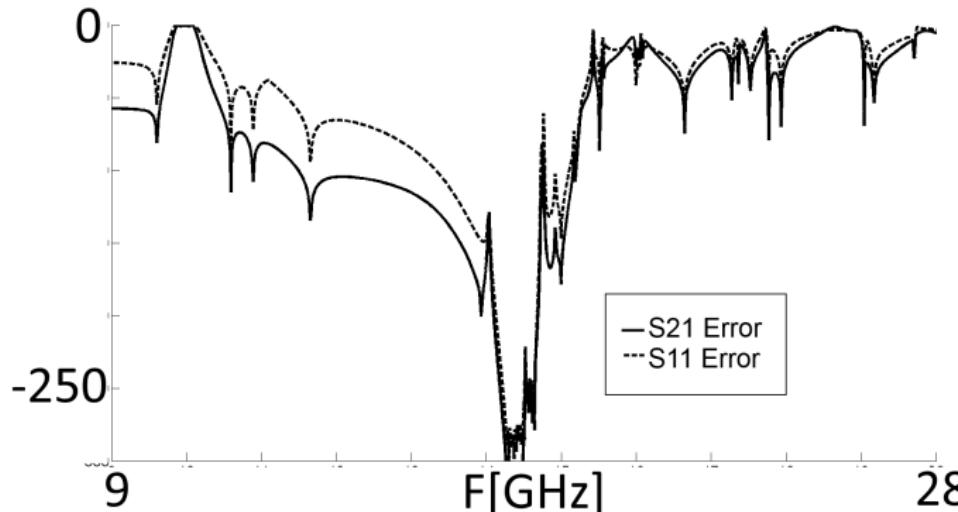
Numerical Experiment

- Waveguide filter with elliptic posts.



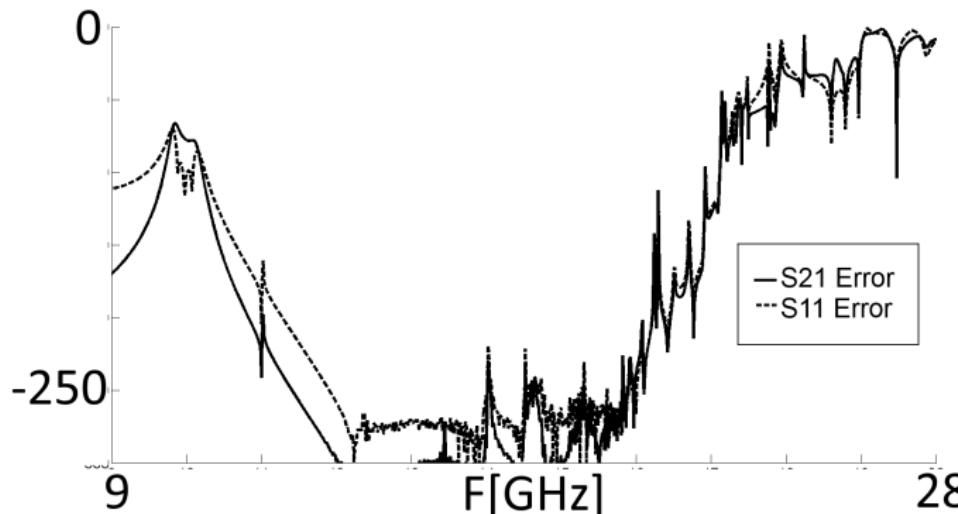
Numerical Experiment

- $q = 10$
 - $20\log(S_{MOR} - S_{FEM})$



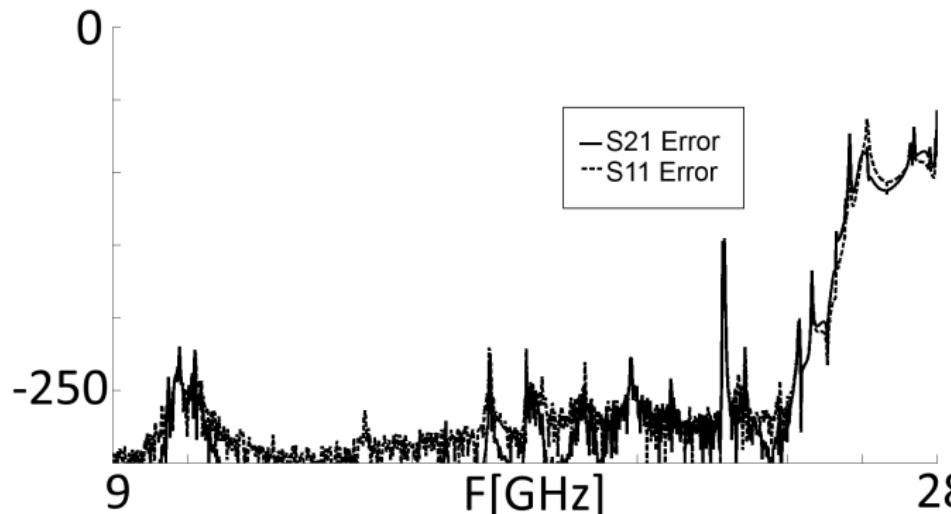
Numerical Experiment

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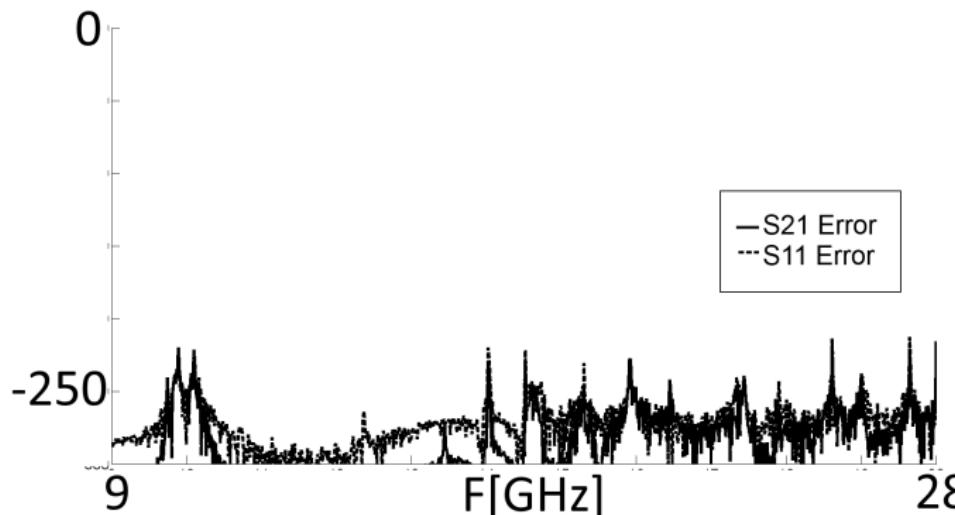
Numerical Experiment

- $q = 40$
- $20 \log(S_{MOR} - S_{FEM})$



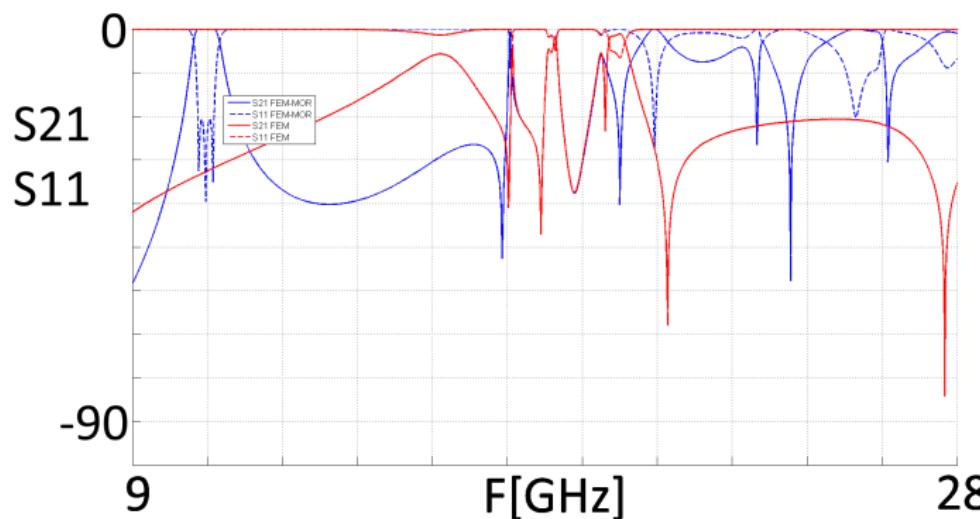
Numerical Experiment

- $q = 70$
- $20 \log(S_{MOR} - S_{FEM})$



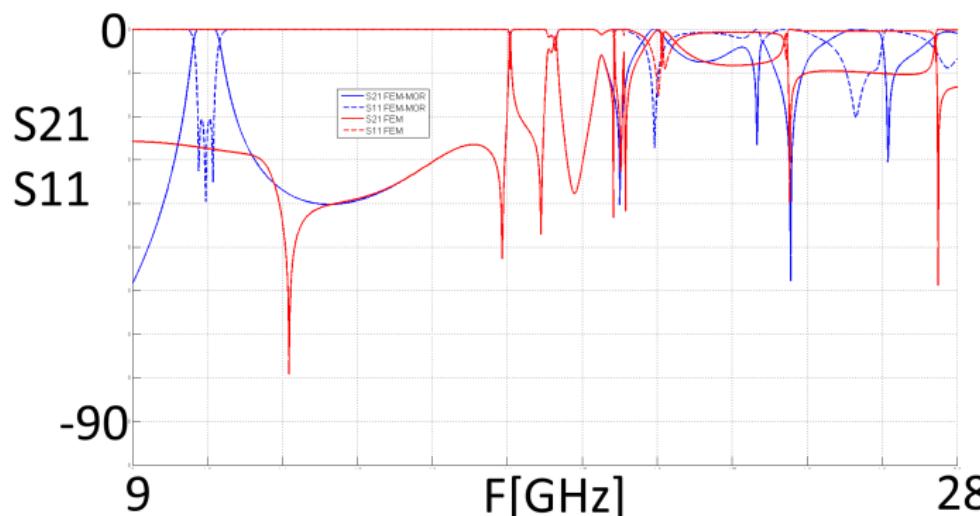
Numerical Experiment

- $q = 5$



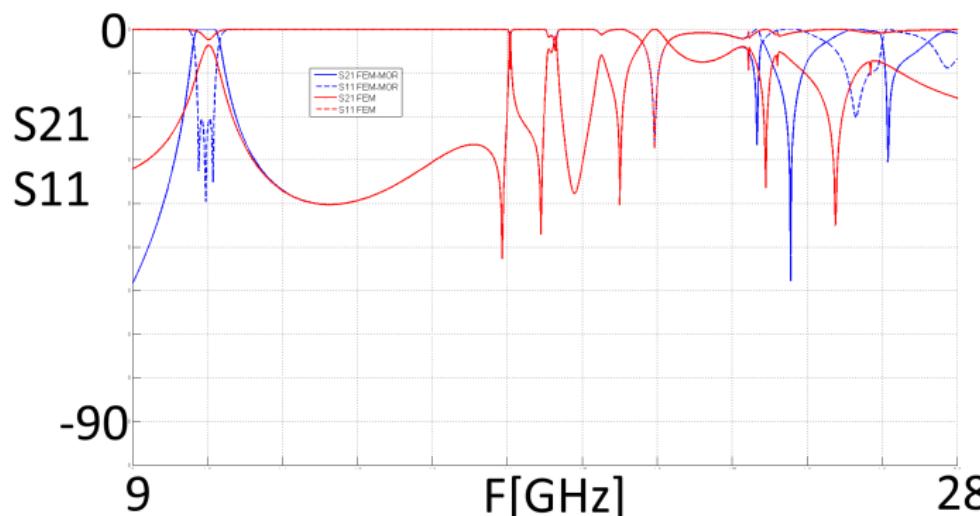
Numerical Experiment

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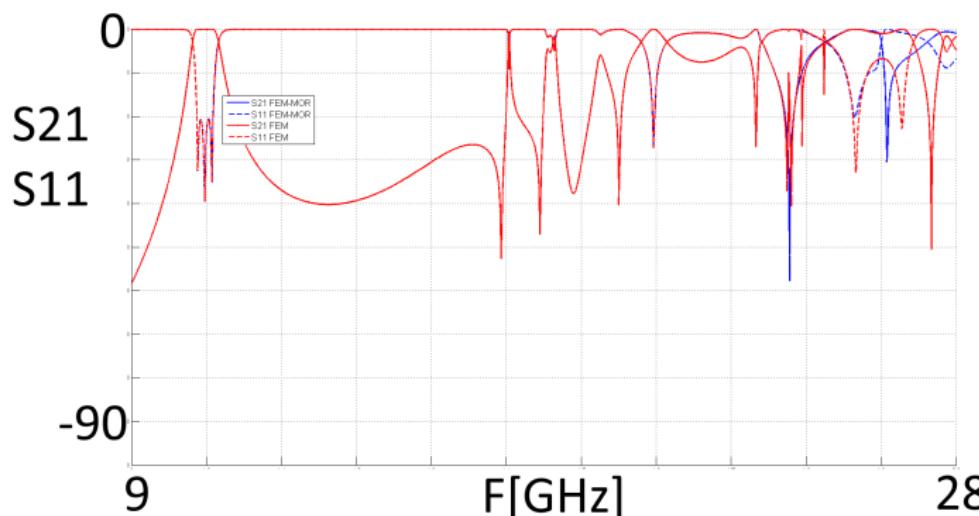
Numerical Experiment

- $q = 15$



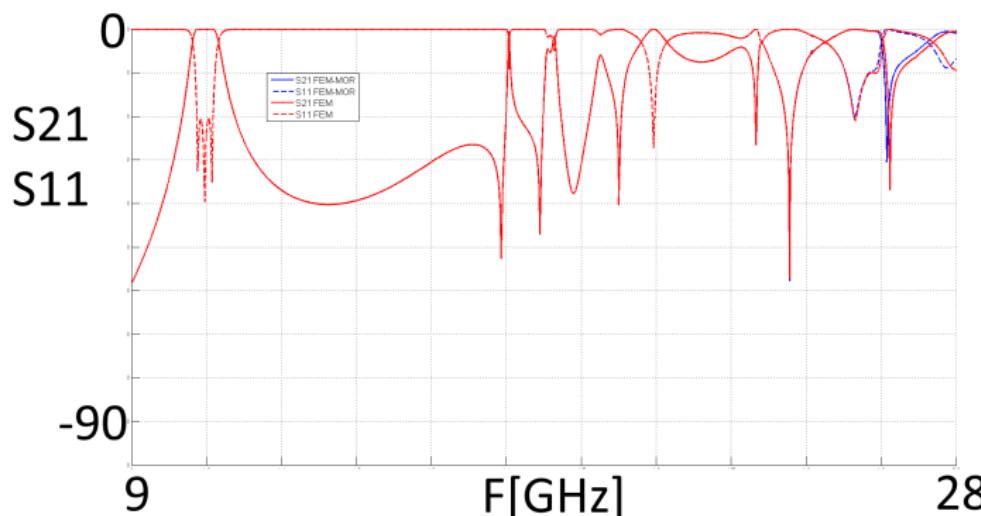
Numerical Experiment

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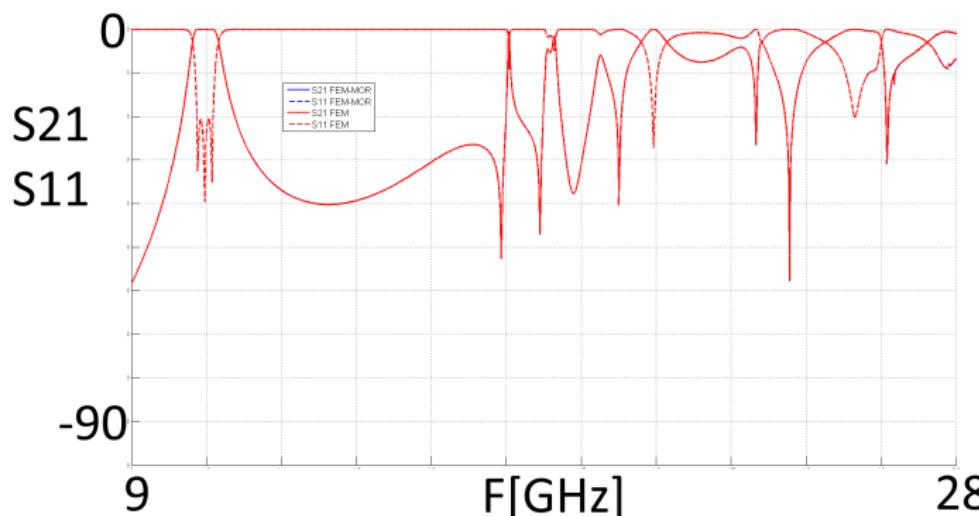
Numerical Experiment

- $q = 25$



Numerical Experiment

- $q = 30$



Error estimation (1)

- The equation for the separated domain

$$(\mathbf{K}_2 - k^2 \mathbf{M}_2) \cdot \mathbf{x}_2 = - (\mathbf{S}_K - k^2 \mathbf{S}_M) \cdot \mathbf{x}_1.$$

- Residuum

$$\mathbf{R}(k) = - (\mathbf{K}_2 - k^2 \mathbf{M}_2) \cdot \mathbf{V} \cdot \tilde{\mathbf{x}}_2 - (\mathbf{S}_K - k^2 \mathbf{S}_M) \cdot \mathbf{x}_1.$$

- Error estimation = Residuum * RHS

$$\begin{aligned} err_{EST}(k) = & \| (\mathbf{S}_K - k^2 \mathbf{S}_M) \cdot \mathbf{R}(k) \| = \| k^4 (\mathbf{S}_M, \mathbf{S}_M) - k^2 (\mathbf{S}_M, \mathbf{S}_K) - \\ & - k^2 (\mathbf{S}_M, \mathbf{K}_2 \cdot \mathbf{V}) + k^4 (\mathbf{S}_M, \mathbf{M}_2 \cdot \mathbf{V}) \cdot \tilde{\mathbf{x}}_2 - k^2 (\mathbf{S}_M, \mathbf{S}_K) + \\ & + (\mathbf{S}_K, \mathbf{S}_K) + (\mathbf{S}_K, \mathbf{K}_2 \cdot \mathbf{V}) \cdot \tilde{\mathbf{x}}_2 - k^2 (\mathbf{S}_K, \mathbf{M}_2 \cdot \mathbf{V}) \cdot \tilde{\mathbf{x}}_2 \|, \end{aligned}$$

Error estimation (1)

- The equation for the separated domain

$$(\mathbf{K}_2 - k^2 \mathbf{M}_2) \cdot \mathbf{x}_2 = - (\mathbf{S}_K - k^2 \mathbf{S}_M) \cdot \mathbf{x}_1.$$

- Residuum

$$\mathbf{R}(k) = - (\mathbf{K}_2 - k^2 \mathbf{M}_2) \cdot \mathbf{V} \cdot \tilde{\mathbf{x}}_2 - (\mathbf{S}_K - k^2 \mathbf{S}_M) \cdot \mathbf{x}_1.$$

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Error estimation (1)

- The equation for the separated domain

$$(\mathbf{K}_2 - k^2 \mathbf{M}_2) \cdot \mathbf{x}_2 = - (\mathbf{S}_K - k^2 \mathbf{S}_M) \cdot \mathbf{x}_1.$$

- ### • Residuum

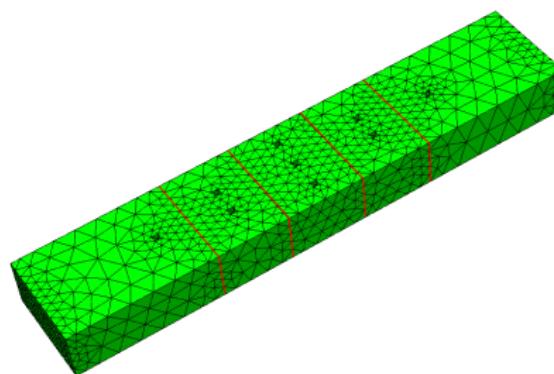
$$\mathbf{R}(k) = -(\mathbf{K}_2 - k^2 \mathbf{M}_2) \cdot \mathbf{V} \cdot \tilde{\mathbf{x}}_2 - (\mathbf{S}_K - k^2 \mathbf{S}_M) \cdot \mathbf{x}_1$$

- Error estimation = Residuum * RHS

$$err_{EST}(k) = \left\| (\mathbf{S}_K - k^2 \mathbf{S}_M) \cdot \mathbf{R}(k) \right\| = \left\| k^4 (\mathbf{S}_M, \mathbf{S}_M) - k^2 (\mathbf{S}_M, \mathbf{S}_K) - k^2 (\mathbf{S}_M, \mathbf{K}_2 \cdot \mathbf{V}) + k^4 (\mathbf{S}_M, \mathbf{M}_2 \cdot \mathbf{V}) \cdot \tilde{\mathbf{x}}_2 - k^2 (\mathbf{S}_M, \mathbf{S}_K) + (\mathbf{S}_K, \mathbf{S}_K) + (\mathbf{S}_K, \mathbf{K}_2 \cdot \mathbf{V}) \cdot \tilde{\mathbf{x}}_2 - k^2 (\mathbf{S}_K, \mathbf{M}_2 \cdot \mathbf{V}) \cdot \tilde{\mathbf{x}}_2 \right\|.$$

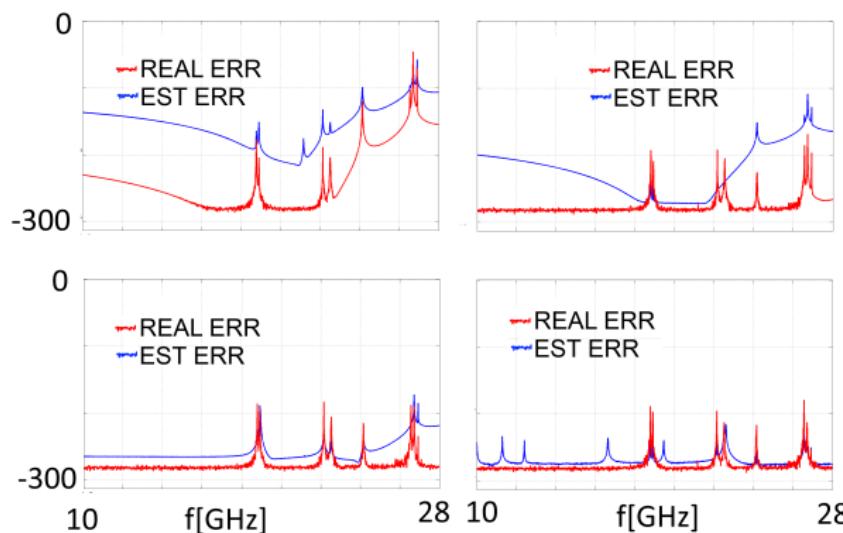
Error estimation (2)

- frequency band: (10,28) GHz



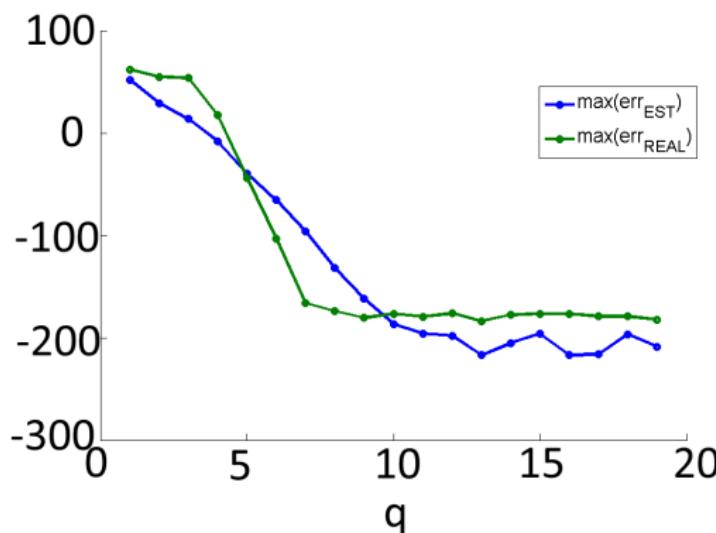
Error estimation (3)

- $q = 5, 7, 9, 12$
- Real error vs estimation



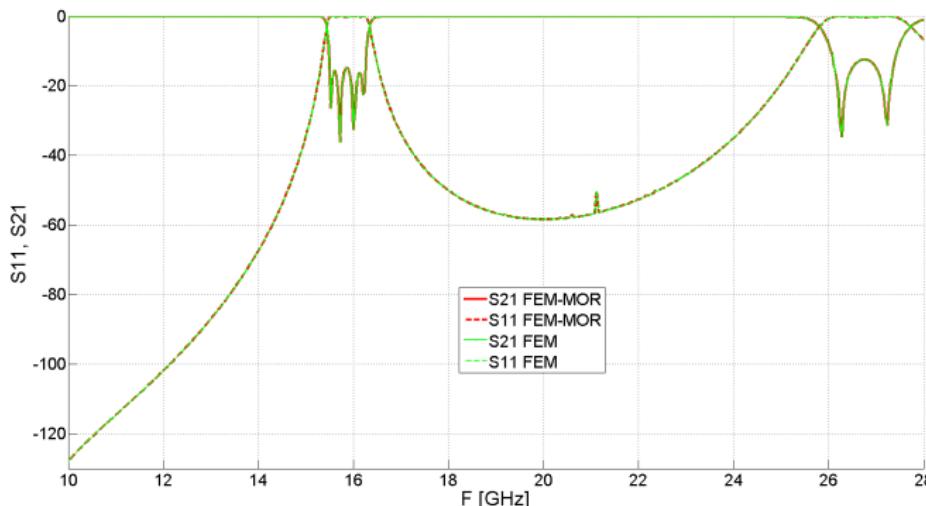
Error estimation (4)

- Integrated plots of real and estimated errors.
- Real error vs estimation



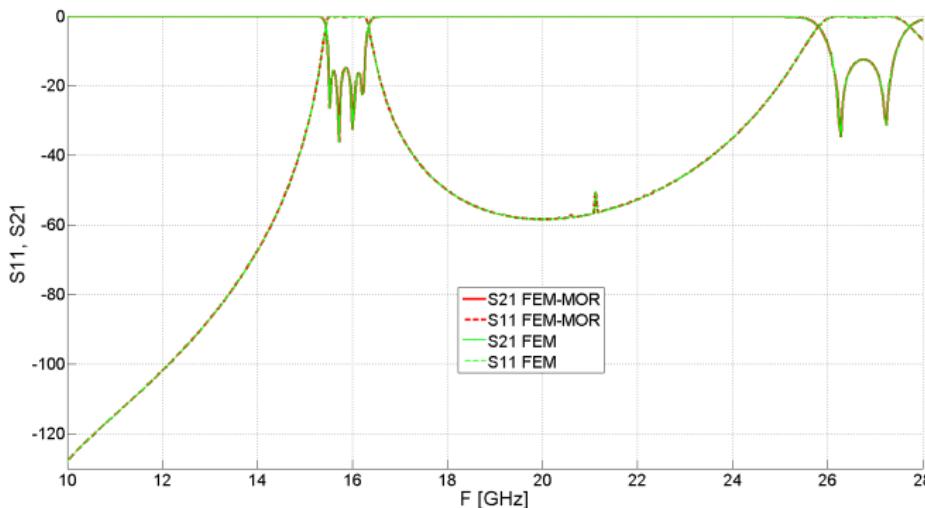
Error estimation (5)

- $\max(\text{errEST}(k)) = 10e-3$
- Automatic selection of $q = \{8; 5; 6; 6; 9\}$



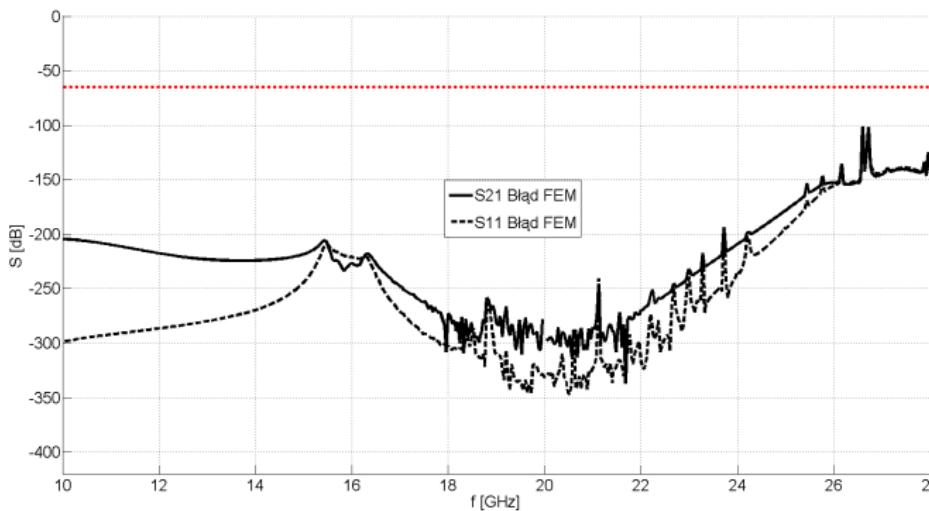
Error estimation (5)

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 - Automatic selection of $q = \{8; 5; 6; 6; 9\}$



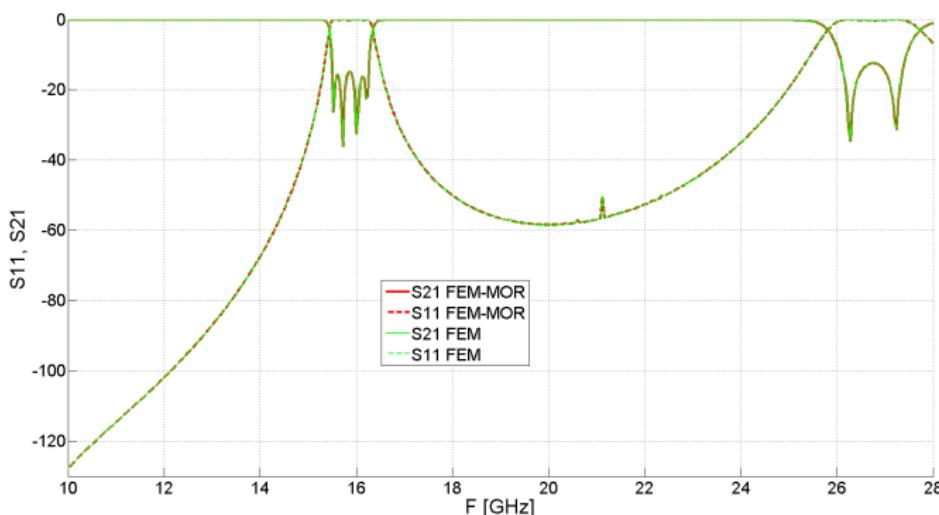
Error estimation (5)

- $\max(\text{errEST}(k)) = 10e-3$
 - Automatic selection of $q = \{8; 5; 6; 6; 9\}$



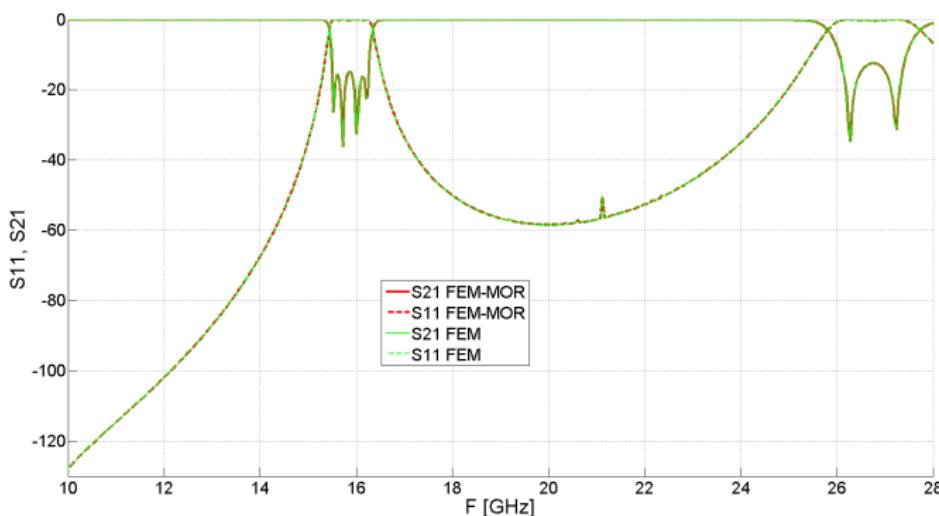
Error estimation (6)

- $\max(\text{errEST}(k)) = 10e-6$
- Automatic selection of $q = \{12; 8; 9; 8; 12\}$



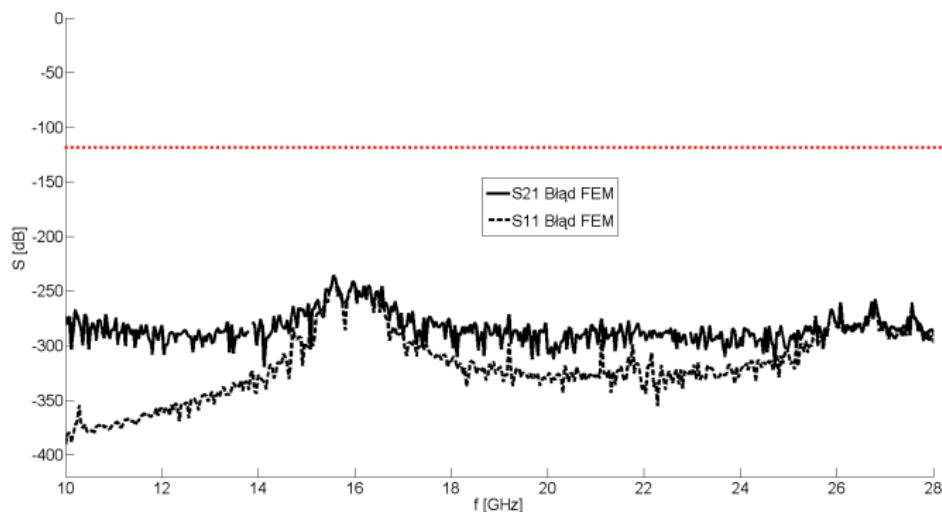
Error estimation (6)

- $\max(\text{errEST}(k)) = 10e-6$
 - Automatic selection of $q = \{12; 8; 9; 8; 12\}$



Error estimation (6)

- $\max(\text{errEST}(k)) = 10e-6$
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Conclusions

- Numerical experiments prove that incorporating reduced - order models into standard 3-D FEM algorithm results in significant reduction of number of variables and time cost, without sacrificing computational accuracy.
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Conclusions

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Thank you for your attention